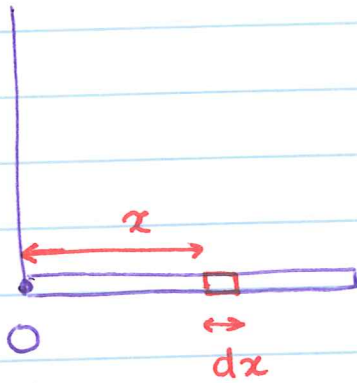


# Moment of Inertia of different Shapes

①



Rod of Mass M  
Length L

anchored at the edge

Break up the rod into small portions of size dx.

$$\text{Density} = \frac{\text{mass}}{\text{length}} \Rightarrow \rho = \frac{M}{L} \quad \text{--- (1.1)}$$

$$dI = \text{moment of inertia of small portion } dx$$

$$= \text{mass of portion} \times \left( \text{distance from axis of rotation} \right)^2$$

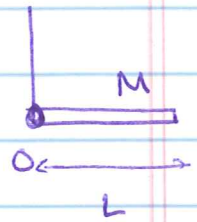
$$= \underbrace{\rho dx}_{\substack{\text{Mass} \times \text{length} \\ \text{length} \\ \text{dimensions of mass}}} \times (x^2)$$

$$I = \int dI = \rho \int_0^L x^2 dx = \rho \left. \frac{x^3}{3} \right|_0^L = \frac{\rho L^3}{3}$$

--- (1.2)

Substitute for  $\rho$  from Eq. (1.1)

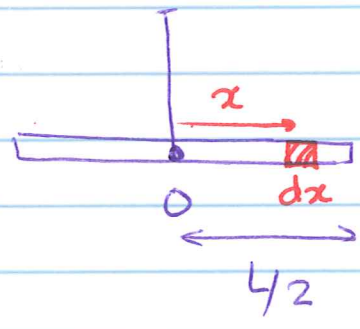
$$I = \frac{M}{L} \frac{L^3}{3} = \frac{1}{3} ML^2$$



$$I_{rod} = \frac{ML^2}{3}$$

about an axis through the edge of the rod.

(2)



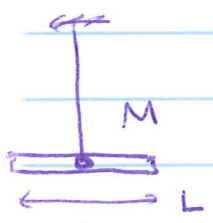
Mass of rod M  
Length L  
axis of rotation through center of rod.

$$dI = \rho dx \cdot x^2$$

$$I = \left[ \rho \int_0^{L/2} x^2 dx \right] \times 2$$

Note upper limit goes only till  $L/2$  and the multiplication by 2 accounts for both left and right sides.

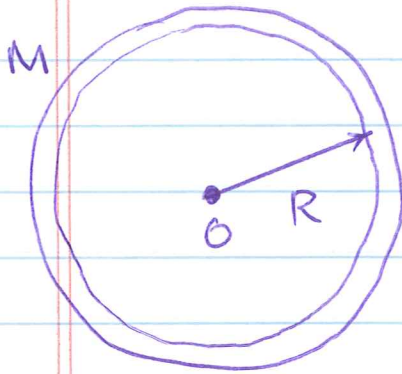
$$I = 2\rho \frac{x^3}{3} \Big|_0^{L/2} = \frac{2\rho}{3} \left(\frac{L}{2}\right)^3 = \frac{2}{3} \frac{M}{L} \frac{L^3}{8}$$



$$I_{rod} = \frac{ML^2}{12}$$

3

③ Hoop (thin hoop - neglect thickness)

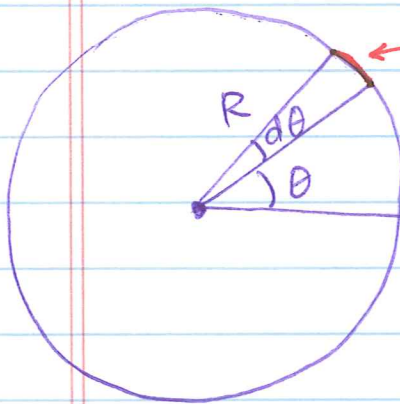


Axis of rotation through center of hoop

Since all the points on the hoop are the same distance away,  $R$ , from  $O$

$$I_{\text{hoop}} = MR^2$$

Can also show this by integration



arc length =  $R d\theta$

$$\frac{\text{Mass}}{\text{Length}} = \rho = \frac{M}{2\pi R}$$

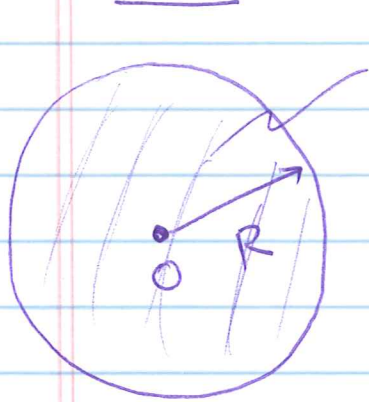
$$dI = \underbrace{(\rho R d\theta)}_{\text{mass of arc length}} R^2$$

$$I = \int dI = \rho R^3 \int_0^{2\pi} d\theta = \frac{M}{2\pi R} R^3 2\pi = MR^2$$

constant for all theta

so it can be pulled out of the integral

④ Disk



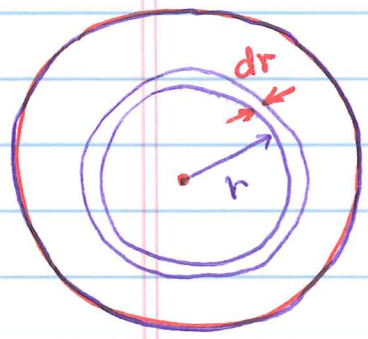
solid

Mass M

Radius R

Axis of rotation through O

Break up the disk into thin hoops.  
The hoops have different radii.



Consider a hoop at a radius r  
with thickness dr

$$\rho = \frac{\text{Mass}}{\text{Area}} = \frac{M}{\pi R^2}$$

$$I_{\text{hoop}} = (dm) r^2 = (\rho \times \text{area of hoop}) r^2$$

$$= \rho (2\pi r dr) r^2$$

$$I_{\text{disk}} = \int I_{\text{hoop}} = \int_0^R \rho (2\pi r dr) r^2$$

$$= 2\pi \rho \int_0^R r^3 dr = 2\pi \rho \frac{R^4}{4}$$

$$= 2\pi \frac{M}{\pi R^2} \frac{R^4}{4} = \frac{MR^2}{2} \Rightarrow I_{\text{disk}} = \frac{MR^2}{2}$$



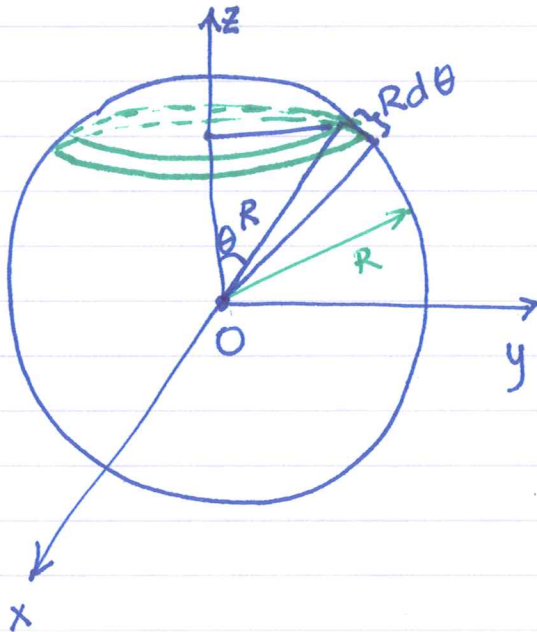
5

### Spherical Hollow Shell:

Axis of rotation along  $\hat{z}$

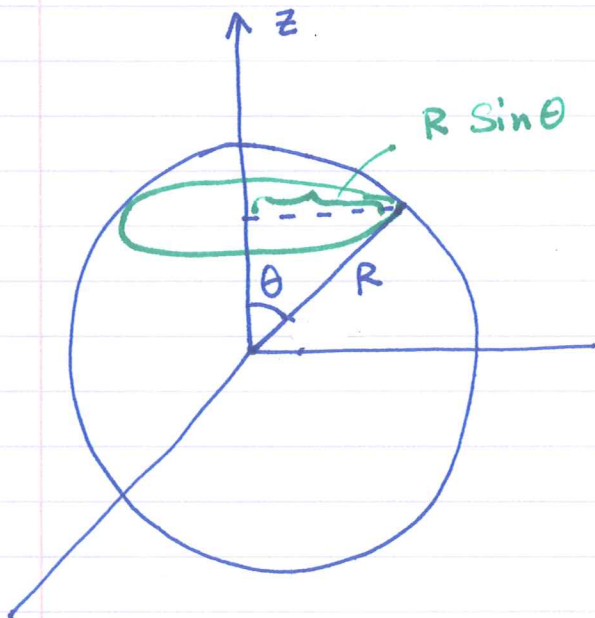
Mass  $M$

Radius  $R$

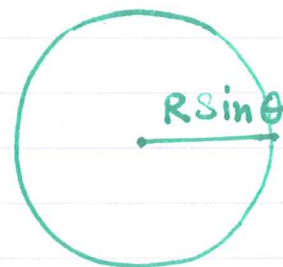


Slice the spherical shell into hoops perpendicular to the  $z$ -axis.

The radius of the hoop varies from zero at the poles to  $R$  at the equator



Top view of hoop



$$\text{Radius of hoop} = R \sin \theta$$

$$\theta = 0 \text{ at } N \text{ pole}$$

$$\theta = \frac{\pi}{2} \text{ at equator}$$

$$\theta = \pi \text{ at } S \text{ pole.}$$

$$\rho = \frac{\text{mass}}{\text{area}} = \frac{M}{\underbrace{4\pi R^2}_{\text{Surface area of Spherical Shell}}}$$

$$\begin{aligned} I_{\text{hoop}} &= (dm) r^2 \\ &= \rho (\text{area of hoop}) r^2 \\ &= \rho (2\pi R \sin\theta \cdot R d\theta) (R \sin\theta)^2 \\ &= 2\pi \rho R^4 \sin^3\theta d\theta \end{aligned}$$

$$\begin{aligned} I_{\text{shell}} &= \int I_{\text{hoop}} = 2\pi \rho R^4 \underbrace{\int_0^\pi \sin^3\theta d\theta}_{\frac{4}{3}} \\ &= 2\pi \frac{M}{4\pi R^2} R^4 \frac{4}{3} \end{aligned}$$

$$I_{\text{shell}} = \frac{2}{3} M R^2$$

Integral of  $\int_0^{\pi} \sin^3 \theta \, d\theta$

$$= \int_0^{\pi} \underbrace{\sin^2 \theta}_{1 - \cos^2 \theta} \underbrace{\sin \theta \, d\theta}_{-d \cos \theta}$$

Let  $\cos \theta = x$

$$= - \int_1^{-1} (1 - x^2) \, dx$$

use negative sign to switch limits.

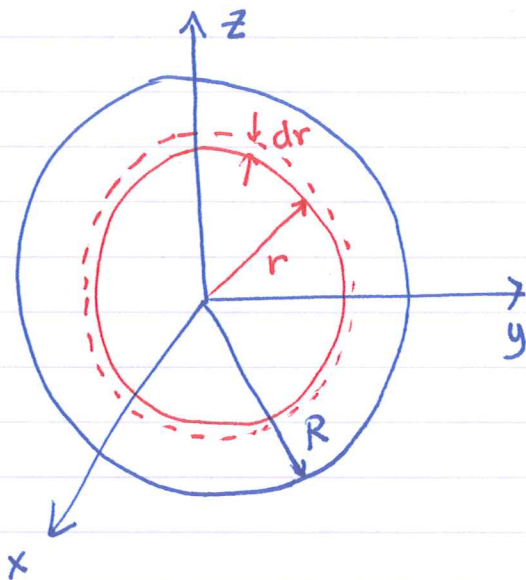
$$= \left( x - \frac{x^3}{3} \right) \Big|_{-1}^1$$

$$= 1 - \frac{1}{3} - \left[ -1 + \frac{1}{3} \right]$$

$$= \frac{2}{3} + \frac{2}{3} = \frac{4}{3}$$

$$\int_0^{\pi} \sin^3 \theta \, d\theta = \frac{4}{3}$$

⑥ Solid Sphere



Axis of rotation along  $\hat{z}$   
Mass  $M$   
Radius  $R$

There are several ways of slicing and dicing the sphere. We could slice it into disks.

The algebra is simpler if we decompose the sphere into shells like an onion.

$$\rho = \frac{\text{Mass}}{\text{Volume}} = \frac{M}{\frac{4}{3} \pi R^3}$$

$$I_{\text{shell}} = \frac{2}{3} (dm) r^2 = \frac{2}{3} \rho (4\pi r^2 dr) r^2$$

$$I_{\text{sphere}} = \frac{2}{3} \frac{M}{\frac{4}{3} \pi R^3} 4\pi \int_0^R r^4 dr$$

$\underbrace{\hspace{10em}}_{R^5/5}$

$$I_{\text{sphere}} = \frac{2}{5} MR^2$$